Electronic Supplementary Material (ESM) for Three-Dimensional Kinematics and the Origin of the Hominin Walking Stride

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ESM Discussion

A comment on measuring pelvis and hip motion. Herein, we include measurements of three-dimensional (3-D) pelvis motion in the global reference frame for bipedal macaques, bipedal chimpanzees and humans walking at similar dimensionless and dimensional speeds (figures 3,S1). Measurement of pelvis motion is essential to computing true 3-D hip motion over a stride (figures 4,S2), and is of direct relevance to studies on the mechanics, energetics and control of facultative and habitual bipedal walking.

The hip flexion-extension measurements herein contrast with most previous studies of facultative bipedal walking (but see 1-2), in which hip flexion-extension has been measured from some approximation of 'trunk inclination' (i.e. tilt). This is most often represented as a vector passing through a hip and a shoulder (or neck/head) marker. 'Hip' flexion-extension is then measured as thigh orientation relative to this vector. This is often a pragmatic solution to the absence of anatomical markers (or other means, e.g. 1) for approximating pelvis motion. However, because the trunk is a non-rigid element – and facultative bipeds are variable in the extent of decoupling of their pelvis and thorax (e.g. 1-3,6,11; figures 3,S1) – this measurement approach may be inadequate for comparing the effects of lower back and ilia design on hip motion during bipedal walking. Indeed, the results herein indicate that bipedal macaques walk with more anterior pelvis tilt (i.e. M v. C: RMSE=9°; table 4) and greater hip flexion (i.e. M v. C: RMSE=9°; table 4) and greater wells (M: ~25°, 6; C: ~30-35°, 4-6).

The absence of direct measurements of pelvis motion in earlier sagittal plane kinematics may underlie some of the interspecific variation in 'hip' flexion-extension among bipedal chimpanzees, macaques, atelids and gibbons (e.g. 7-10), although more measurements of pelvis motion are needed to evaluate this. Of course, un-matched speeds and the lack of variance measures in these earlier comparisons also make it difficult to assess the significance of some of the observed differences. Given this, some caution is warranted when parsing the effects of lower back and/or pelvis size and shape on hip motion using these earlier data (e.g. 11,12).

ESM Discussion References

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Figure S1

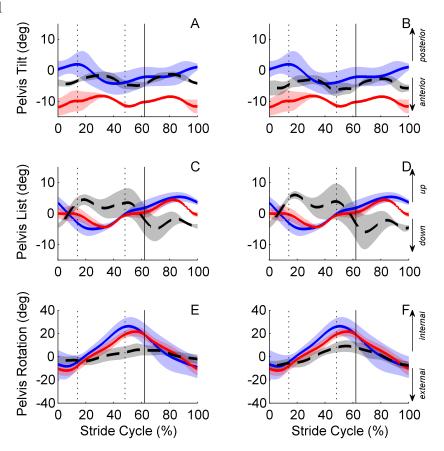


Figure S1. The pelvis (A-B) tilt, (C-D) list and (E-F) rotation angles, relative to the global coordinate system, over a walking stride (mean \pm s.d.) for macaques (solid red line), chimpanzees (solid blue line) and humans (dashed black line) at similar dimensional (H: $v=1.08 \text{ m s}^{-1}$; column 1) and dimensionless velocities (H: $v=1.66 \text{ m s}^{-1}$; column 2). Each stride begins and ends at ipsilateral heel strike. Gait cycle and events are as in figure 3.

Figure S2

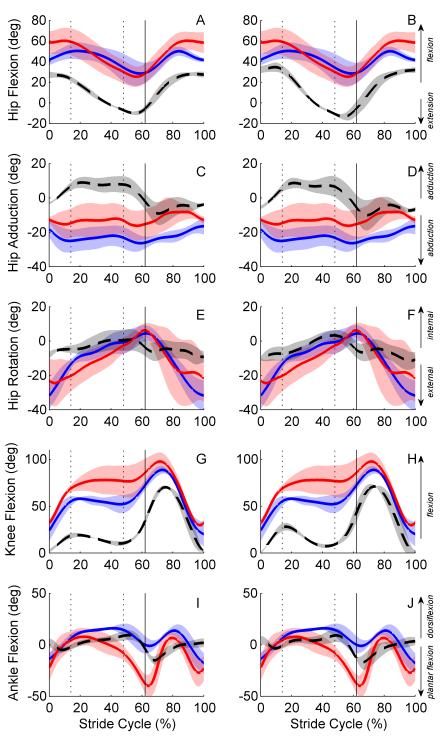


Figure S2. The hip (A-B) flexion, (C-D) adduction, (E-F) rotation, (G-H) knee flexion and (I- J) ankle flexion angles over a walking stride (mean \pm s.d.) for macaques and chimpanzees and humans (dashed black line) at similar dimensional (H: $v=1.08 \text{ m s}^{-1}$; column 1) and dimensionless velocities (H: $v=1.66 \text{ m s}^{-1}$; column 2). Each stride begins and ends at ipsilateral 'heel strike'. Gait cycle and events are as in figure 4.

Table S1. Zero-lag cross-correlations (r) of macaque (M), chimpanzee (C) and human (H) pelvis and hind limb motion over a full stride for walking at similar dimensional velocities.

	Pelvis	Pelvis	Pelvis	Hip	Hip	Hip	Knee	Ankle
	Tilt	List	Rotation	Flexion	Adduction	Rotation	Flexion	Flexion
M v. H	0.964	-0.660	0.901	0.822	-0.284	0.830	0.850	0.189
C v. H	0.521	-0.834	0.760	0.739	-0.233	0.860	0.901	0.315

Table S2. Root mean square error (RMSE) of macaque (M), chimpanzee (C) and human (H) pelvis and hind limb motion over a full stride for walking at similar dimensional velocities.

	Pelvis	Pelvis	Pelvis	Hip	Hip	Hip	Knee	Ankle
	Tilt	List	Rotation	Flexion	Adduction	Rotation	Flexion	Flexion
M v. H	7°	5°	9°	35°	16°	11°	48°	16°
C v. H	3°	6°	11°	32°	25°	11°	33°	11°